

20th IAA SYMPOSIUM ON HUMAN EXPLORATION OF THE SOLAR SYSTEM (A5)
Interactive Presentations (IP)

Author: Mr. Oleg Aleksandrov
Private individual www.oleg.space, United States

PILOTED ROVERS FOR EXPLORATION OF THE MOON, MARS AND OTHER PLANETS

Abstract

This concept will allow to perform a wide range of scientific and geological problems during one mission over a large area. Rovers will be equipped with cluster dredge devices allow you to collect soil samples from a depth of over 150 meters. Radius of the rovers will be more than 1,000 kilometers. The risks of not returning to the place of landing for these modules do not exist because the rovers expected to supply rocket returnable fuel for which may be produced during the movement of planetary rovers. Rovers will be equipped with docking ports through which a plurality of planetary rovers can form the station and even villages. Bussines card of the project is additional inatable modules extends the internal volume of the stations for the crews. Such rovers will be equipped with landing systems with the soft landing right on the wheels. The project is now in the stage of development of technical documentation for the construction and testing of the key systems.