student

IAF SPACE EXPLORATION SYMPOSIUM (A3) Interactive Presentations - IAF SPACE EXPLORATION SYMPOSIUM (IP)

 ${\bf Author:~Ms.~SHAMBHAVI~A~S}$ Nitte Meenakshi Institute of Technology, India, shambhavias14@gmail.com

Dr. Prahalad N Tengli

Nitte Meenakshi Institute of Technology, India, prahalad.n@nmit.ac.in Mr. Sanath Kumar Naik L

Nitte Meenakshi Institute Of Technology., India, snaik6073@gmail.com Mr. Amaranath Siddaraddi

Nitte Meenakshi Institute of Technology, India, amarss369@gmail.com Mr. Prabhanjan Manjunath

Manipal Institute of Technology, India, prabhanjanmram@gmail.com Mr. Rohan Shinde

Manipal Institute of Technology, India, shinde.rohan0311@gmail.com Mr. Amit S Herkal

Nitte Meenakshi Institute of Technology, India, amitherkal@gmail.com Mr. Vivekananda N

Nitte Meenakshi Institute of Technology, India, vivekvivekananda10@outlook.com

SWARM UAVS: A NOVEL APPROACH FOR EFFICIENT REMOTE SENSING ON MARS

Abstract

Mars exploration and the collection of valuable scientific data in the remote and hostile environment of the red planet are challenging tasks. Remote sensing plays a critical role in this endeavor, allowing for the collection of data on Mars from a distance without physical contact. Unmanned Aerial Vehicles (UAVs) are a promising solution for remote sensing on Mars, but their deployment poses significant challenges, including limited range, environmental hazards, and difficult terrain. To address these challenges, a novel approach is proposed, the use of swarm UAVs for remote sensing on Mars. A swarm is a group of small UAVs that operate together as a collective, using coordinated algorithms to achieve a common goal. Swarm UAVs can be programmed to navigate and perform tasks autonomously, making them ideal for remote sensing applications. Swarm UAVs can operate in hazardous environments, including areas with steep terrain, high winds, and dust storms, which are common on Mars. The proposed system comprises a group of small, lightweight UAVs equipped with a range of remote sensing technologies, including highresolution cameras, spectrometers, and lidar systems. The UAVs will be designed to operate as a swarm, communicating with each other to coordinate their movements and avoid collisions. The swarm will be controlled from a primary satellite in the constellation. The swarm UAVs will be capable of collecting data over a large area quickly, enabling more extensive coverage of the Martian surface than is currently possible with traditional remote sensing techniques. The data collected by the swarm will be transmitted back to Earth, where it will be analyzed by scientists and used to better understand the Martian environment. The suggested method of swarm UAV system represents a significant step forward in Mars exploration and remote sensing capabilities. By leveraging the collective intelligence of a swarm, many of the challenges associated with traditional UAVs can be overcome and also achieve a more extensive and efficient coverage of the Martian surface. The use of swarm UAVs for remote sensing on Mars will enable breakthrough discoveries and contribute significantly to our understanding of the red planet.